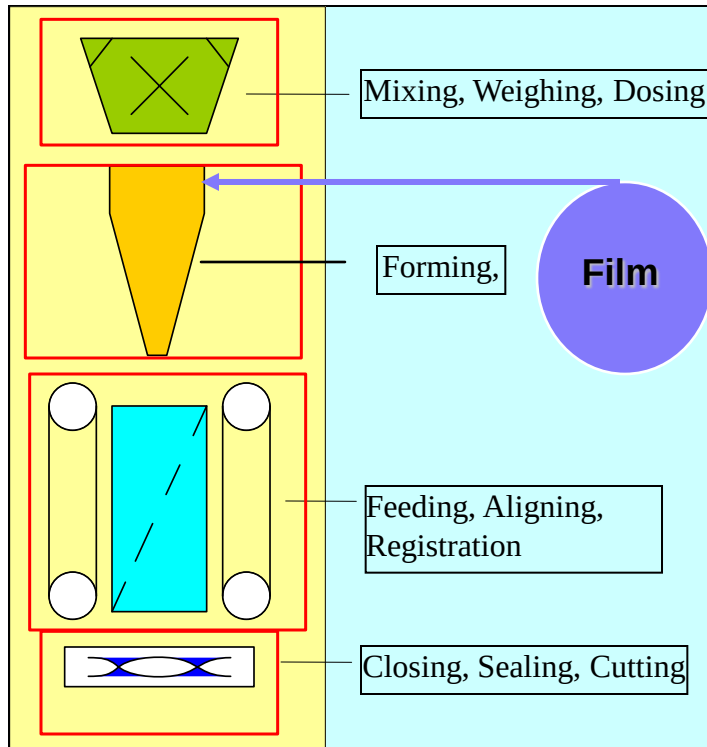


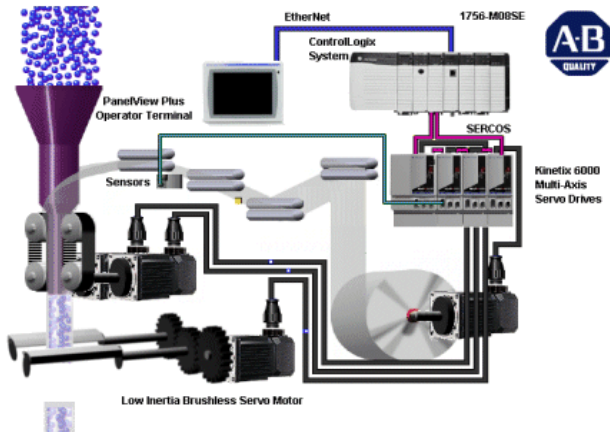
Vertical Form fill and Seal Machine立式包装机



- **Mixing, Weighing, Dosing**混合/称量/给料
 - Product is metered for entry into package产品在包装前的定量
 - Can be liquid or a solid可以是液体或固体
- **Film Feed & Forming**薄膜输送和成型
 - Film is fed and formed into package薄膜被传送和折成圆筒形
- **Feeding, Aligning and Registration**拉膜，纠偏和色标检测
 - Correct amount of package is fed拉送正确袋长
 - Package is aligned with product袋子与包装物同步
- **Closing, Sealing, Cutting**封合，裁断
 - Package with product is closed包装袋闭合
 - Package with product is sealed包装袋热封

Vertical Form fill and Seal Machine立式包装机

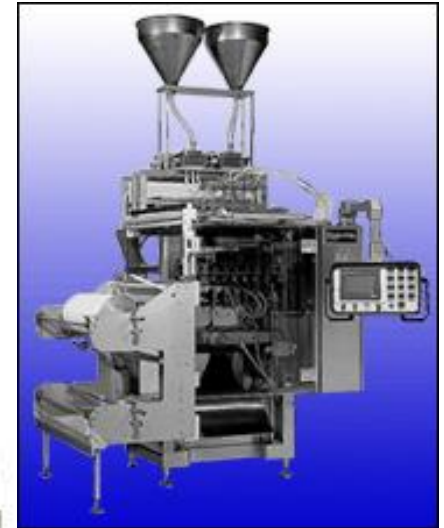
Vertical Form, Fill and Seal using Kinetix 6000



- Mixing, Weighing, Dosing混合/称量/给料
 - Product is metered for entry into package产品在包装前的定量
 - Can be liquid or a solid可以是液体或固体
- Film Feed & Forming薄膜输送和成型
 - Film is fed and formed into package薄膜被传送和折成圆筒形
- Feeding, Aligning and Registration拉膜，纠偏和色标检测
 - Correct amount of package is fed拉送正确袋长
 - Package is aligned with product袋子与包装物同步
- Closing, Sealing, Cutting封合，裁断
 - Package with product is closed包装袋闭合
 - Package with product is sealed包装袋热封
 - Package with product is cut包装袋裁断

Type of VFFS machines 立式包装机类型

- Intermittent & Continuous 间断式&连续式
- Exposed and enclosed 开放式&封闭式
- Single lane (Vertical Pouch, Sachet Form, Fill and Seal machine) 单头
- Multi-lane (Vertical Strip Packing Machine) 多头



Different Style Feeding Systems不同类型的给料系统



Auger Feeder
螺旋式



Multi-head Scale
多头秤



Volumetric Feeder
定体积给料

Machine Sections 机器分段

- Feeding System 给料系统

- Film Unwind 薄膜放卷

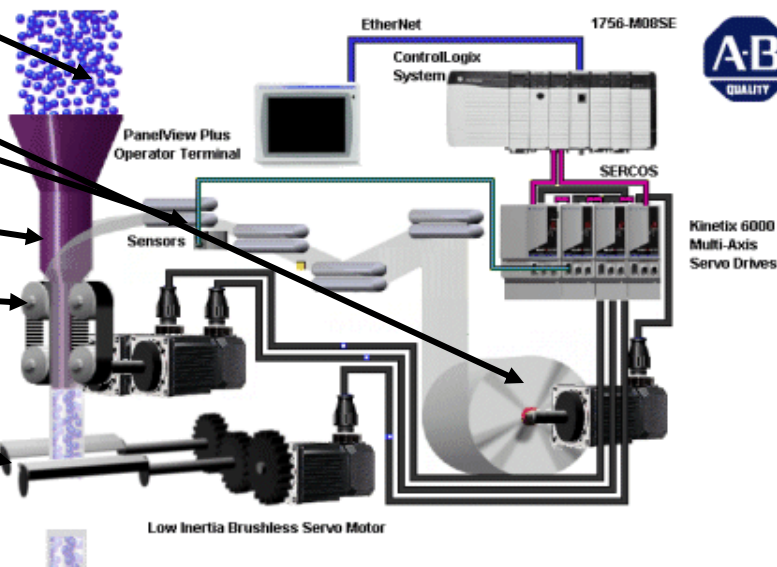
- Film Registration 薄膜色标检测

- Forming Tube 成型筒

- Film Pull Belts 拉膜皮带

- Cross Jaws 横封口

Vertical Form, Fill and Seal using Kinetix 6000



Machine Sections - Feeding System给料系统

- Auger Filler螺旋式给料
 - Typically servo fed – Index moves通常为伺服给定-索引运动
 - VFFS can control the auger or communicate via discrete signals
VFFS可以直接控制螺旋式给料系统或者通过开关量信号通讯
- Weighing System称重系统
 - Mostly controlled by a specialized controller大多由专门的控制器来控制
 - VFFS communicates via discrete signals
VFFS通过开关量信号通讯
- Volumetric Feeder定体积给料
 - Can be servo actuated or pneumatic actuated可以用伺服驱动或者气缸驱动
 - VFFS can control the feeder or communicate via discrete signals
VFFS可以直接控制或者通过开关量信号通讯

Machine Sections - Feeding System给料系统

Product Type	Example	Machine Sections	Application Needs
Liquid	Sauce	Dosing	The machine must manage the measurement and insertion of product into the pouch, which requires tight coordination with the scales, augers, and mixers.
Fine granules	Sugar, Salt	Dosing, Mixing	
Coarse granules	Cereals, Spices	Dosing, Mixing	
Powders	Detergent	Dosing, Mixing	
Solids	Candy, Pharmaceuticals, Hardware	Weighing	For perishable product, the machine needs to be washed down for sanitary purposes.
Fresh produce	Vegetable	Dosing, Gas Flushing for product protection, Wash down	For food products, gas flushing with inert gas or O ² extraction is required to extend food shelf life.
Perishable	Meat, Fish	Dosing, Gas Flushing for product protection, Wash down	

- **Scale Interface**
- The scale interface is the most complex section of a VFFS's control. This is a result of the speeds at which a continuous motion VFFS can run. The VFFS needs to be able to run in either a master mode where a scale drops product upon request from VFFS machine or in slave mode where the scale tells the VFFS when to make a new bag. Due to the high speed of the VFFS machine, multiple charges from the scale can be in flight at one time. This means that product tracking is required to know when to start and stop the VFFS at the proper times. This logic controls the virtual master that runs the position cams for the film pull belts and seal jaws, as such it is the primary module that should be developed first.

Machine Sections - Film Unwind 薄膜放卷

- This section is responsible for unwinding film into the machine
这部分负责薄膜放卷输送给机器
- Material splice, roll change out and film tension need to be considered
接料，换卷和薄膜张力需要被考虑
- Powered or Unpowered, pneumatic brake, friction brake or a dancer control can be used to control film tension.
主动或者被动，风闸，磁粉刹车或者摆动辊可以被用来控制薄膜张力
- Stepper, servo, DC gearmotor, or VFD are used depending on overall performance of machine
步进，伺服，直流电机或者变频驱动都可以实现，选用哪种由整机的性能决定
- Roll change out and material splice can be manual or automatic
换卷和接料可以是手动的也可以是自动的

Machine Sections - Film Registration 薄膜色标检测

- Film registration sensor, film alignment and tracking adjustment mechanisms
包括色标传感器，薄膜纠偏调整机构
- Registration marks on printed film to adjust for printing errors, film stretch and slippage.
通过检测色标可以调整因印刷误差，薄膜拉伸和打滑造成的误差
- Registration control is performed differently with continuous versus intermittent machines.
连续式机器和间断式机器的色标控制方式是不同的
- Registration adjustments are usually made on every index with an intermittent machine.
间断式机器的色标调整通常是每一个袋长都会调整
- Continuous machines registration is usually done by averaging the distances and making minor adjustments if the averages start to drift.
连续式机器的色标调整通常是取一段距离的平均值，如果发生偏移执行最小偏移量的调整

Machine Sections - Forming Tube成型筒

- Unique mechanical designs for different machines, films and products being sealed.
根据不同的机器，薄膜材料以及产品要求有独特的机械设计
- General description – inverted cone with radius corners.
通常的形式-带半角的倒锥体
- Used to convert flat film into a tubular or tunnel shape – film travels on the outside of the forming tube
通常将薄膜转变成筒状或管状-薄膜在成型筒的外部通过
- Film is sealed (long seal) in this section of the machine via several methods – heated bars or heated metal belts are two methods.
在这一部分薄膜通过几种方式被纵封-加热棒或者加热的金属皮带
- Bar is usually stationary
加热棒通常是固定的
- Metal belts have heat transferred to them and move with the product
金属皮带传导热量并且跟随产品运动
- Film is either over wrapped and sealed on one end or sealed on the edges
薄膜被封住一边
- PID controlled heating elements via the main controller or separate stand alone PID controllers
加热条的PID控制可以通过主控制器也可以通过单独的PID控制器控制

Machine Sections - Film Pull Belts拉膜皮带

- Typically two belts right and left side
通常有左右两根皮带
- Typically vacuum which allows for better gripping
通常用真空可以获得更好的吸力
- Belts are controlled by either servo, induction motors or steppers.
皮带由伺服，感应马达或者步进控制
- Two motors for both belts or one motor mechanically linked to both belts
两个马达驱动两根皮带或者一个马达驱动通过机械连接两根皮带
- Belts provide the force to pull the film through the machine
皮带提供摩擦力拉动薄膜穿过机器
- Controller code either uses electronic CAM control or incremental moves dependant on type of machine.
根据机器类型不同，控制代码可以用电子凸轮或者增量运动
- Controller code used to monitor the velocity and/or position between the belts so one belt doesn't pull more than the other.
程序监控两根皮带的速度和/或位置以保证一根皮带没有拉更多薄膜
- Registration correction code is applied to this section
色标纠正代码作用在这段

Machine Sections - Cross Jaw横封口

- Three major functions:
三个主要功能:
 - Seal the top of the previous bag
封住前一袋的顶部
 - Create the bottom for next bag
生成下一袋的底部
 - Cut or separate the bags
剪切或者分隔袋子
- Front and back jaws oppose each other – sometimes one moves and sometimes they both move
前后相对的一对横封条-有时只有一条运动，有时两条都动
- One jaw usually contains a knife and other an anvil. Knife is sometimes actuated pneumatically
通常一个横封条上带了一把刀而另一个横封条做砧。刀有时由气缸推动。
- Intermittent machine – cross jaw section is stationary (doesn't follow film). Film starts and stops
间断式机器-横封口是固定的（不跟随薄膜上下运动），薄膜有启停
- Continuous machine – cross jaw section follows the film
连续式机器-横封口跟随薄膜运动
 - Rotary Jaw (“D” Jaw) – special mechanism to cause “D” motion
旋转式（“D”型）-特殊的机械设计实现”D”形运动
 - Vertical Jaw – two separate moving mechanisms – seal and follow
垂直型-两个独立的运动机构-横封和上下跟随
- Servos, Induction, Stepper motors or Pneumatics, sometimes with springs used for actuation of Jaws.
伺服，感应电机，步进或者气缸，有时甚至弹簧都可驱动横封口
- PID control of heating elements
加热条的PID控制
- Controller code using electronic CAM used for continuous machine
连续式机器要应用电子凸轮编程

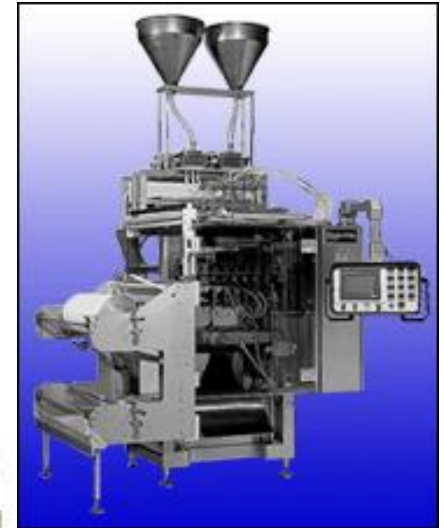
Machine Section Controls 机器分段的控制方式

- Feeding System 给料系统
 - Discrete control, servo control 离散控制, 伺服驱动
- Film Unwind 薄膜放卷
 - Discrete control, servo, VFD, analog dancer 离散控制, 伺服, 变频, 模拟量
- Film Registration 色标检测
 - Registration sensor 色标传感器
- Forming Tube 成型筒
 - PID control PID 控制
- Film Pull Belts 拉膜皮带
 - Discrete control, servo, VFD 离散控制, 伺服, 变频
- Cross Jaws 横封口
 - Discrete control, servo, VFD, PID 离散控制, 伺服, 变频, PID 控制

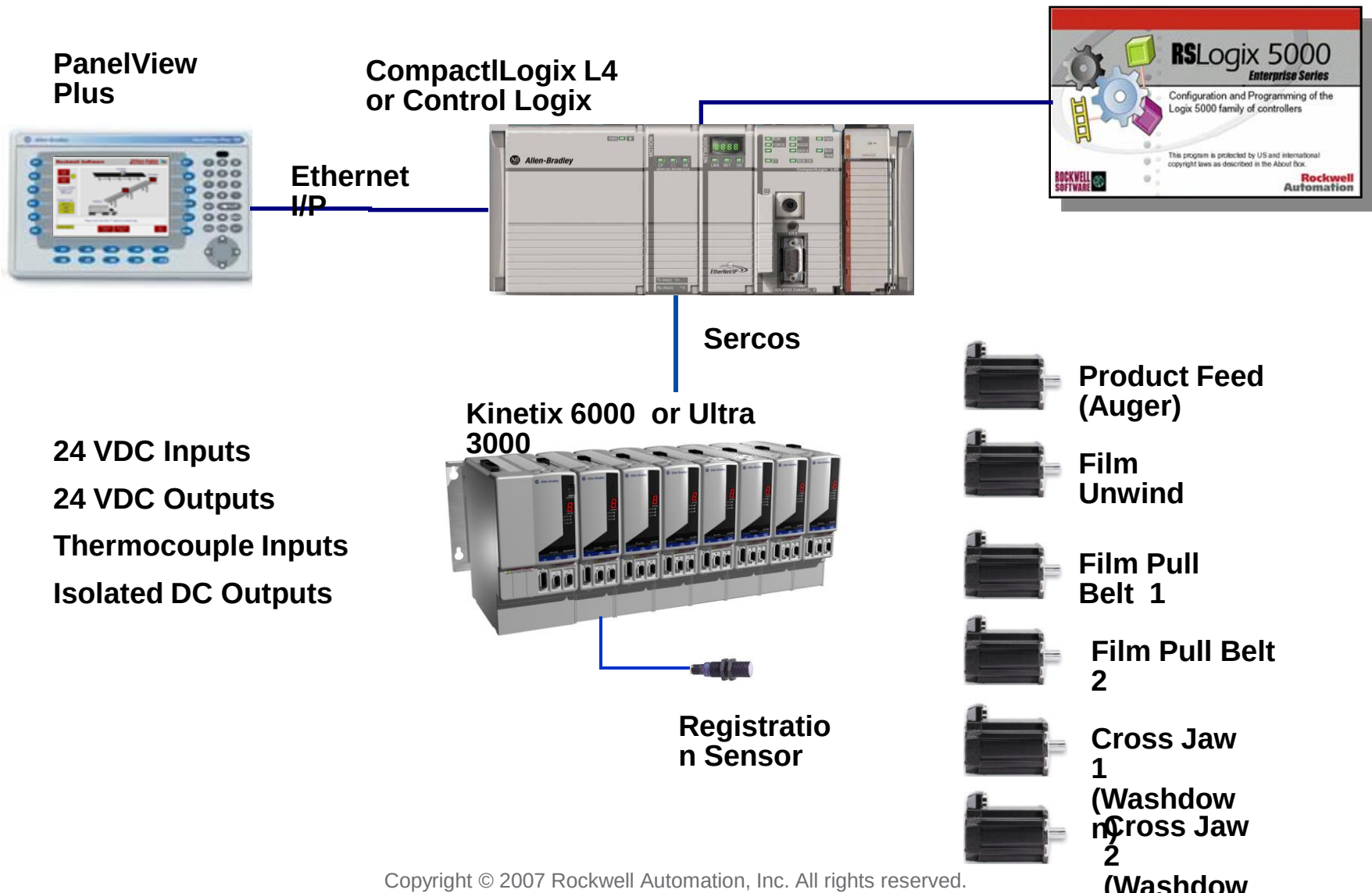
VFFS machines

VFFS machines controls can vary from all servo control to use of VFD's, steppers, mechanical or pneumatic driven actuators.

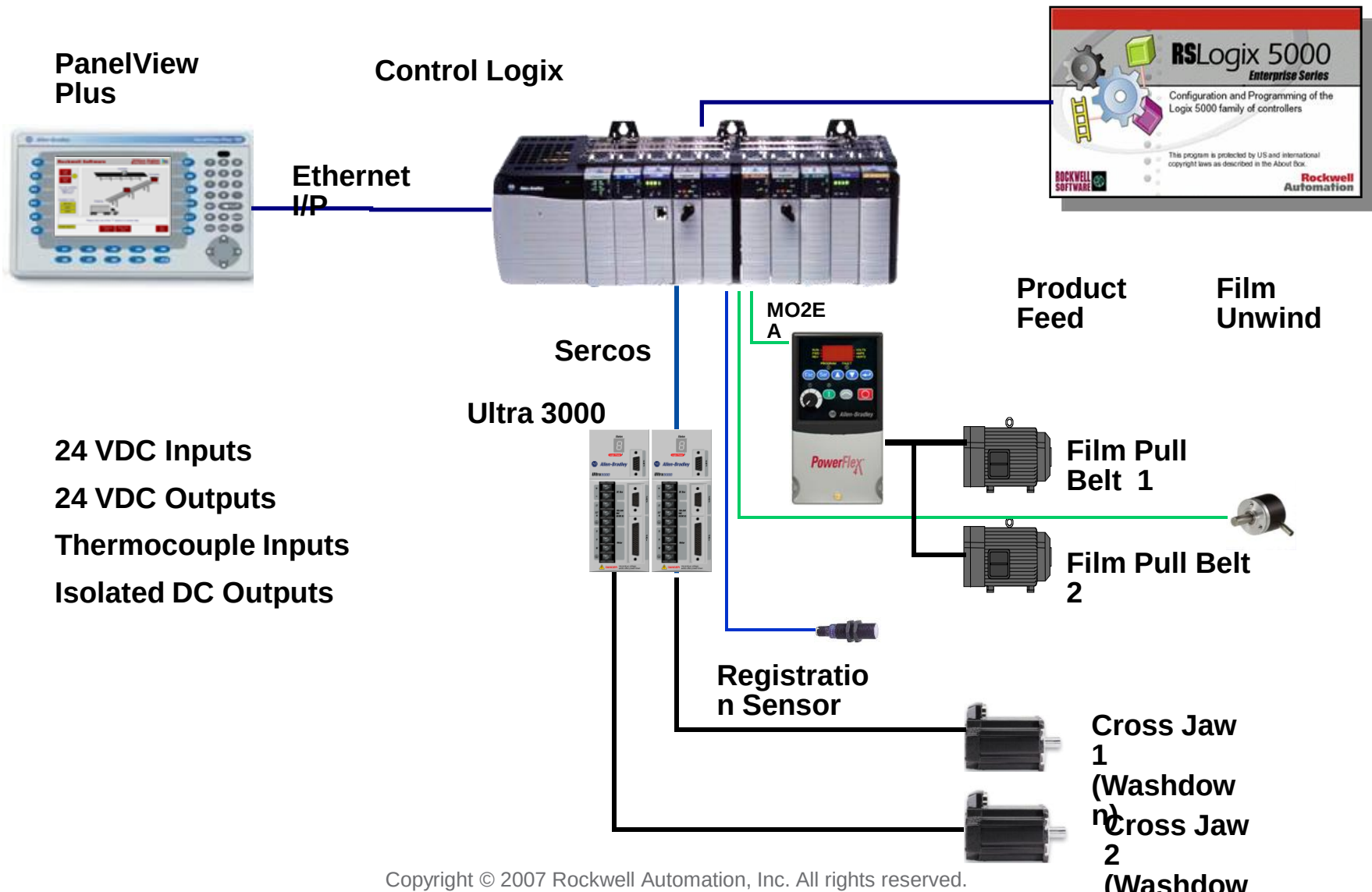
VFFS机器的控制可以从全伺服控制到用变频驱动，步进，机械方式或者气缸驱动都可



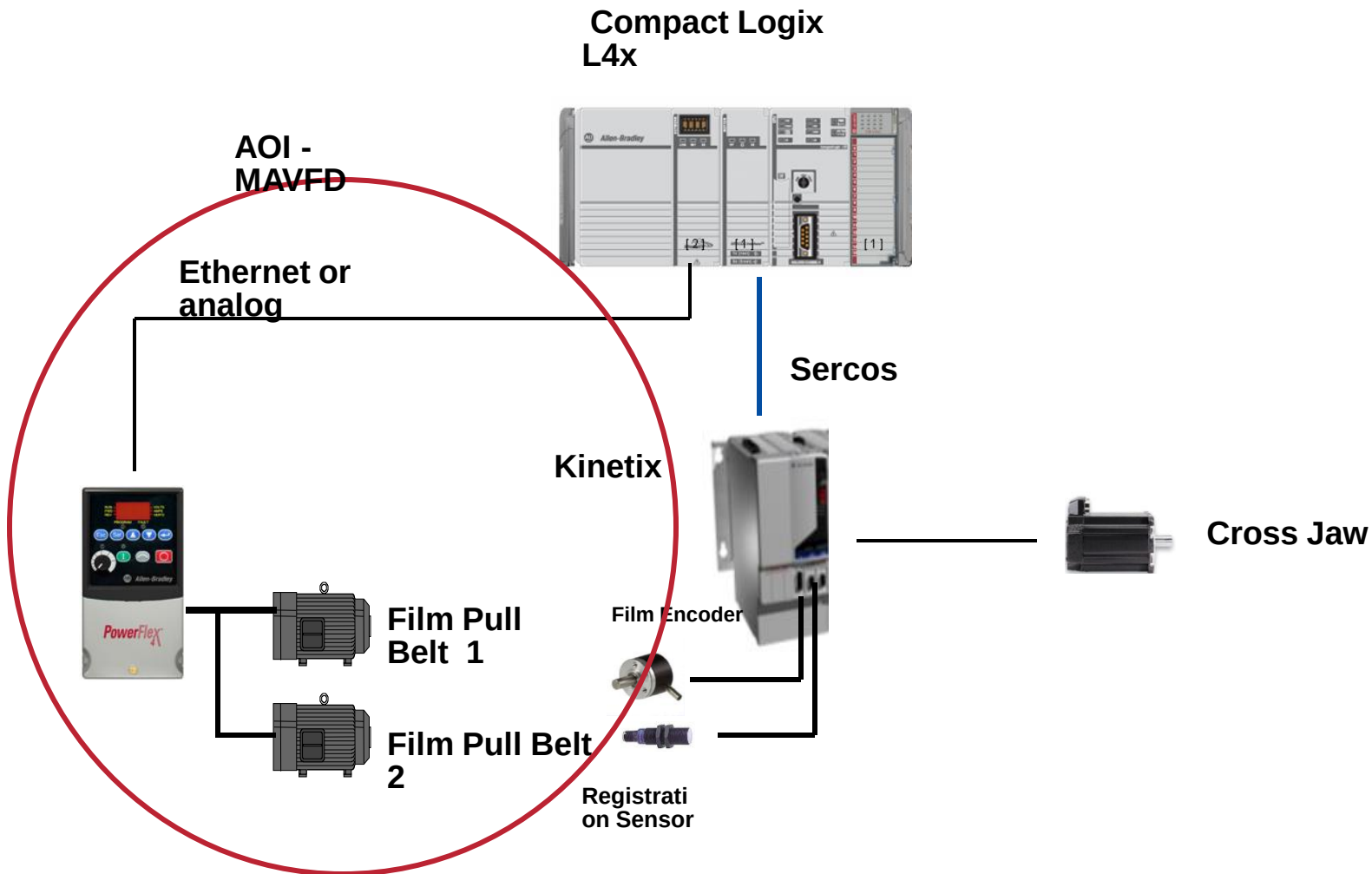
VFFS machine - RA Solution - All Servo全伺服



Example of a VFFS using VFD 含变频驱动的例子

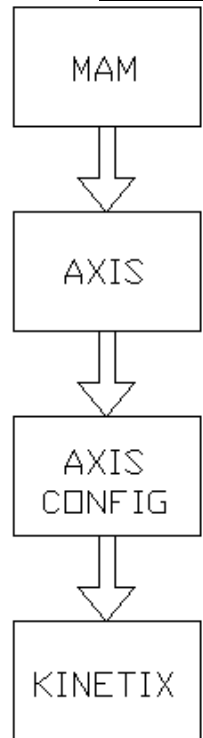


RA Solution - Lower End VFFS 最低端方案

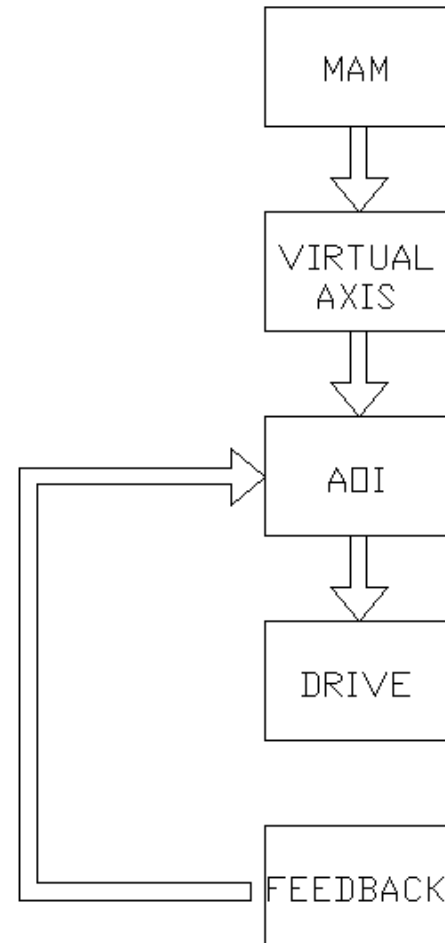


MAVFD AOI: Concept概念

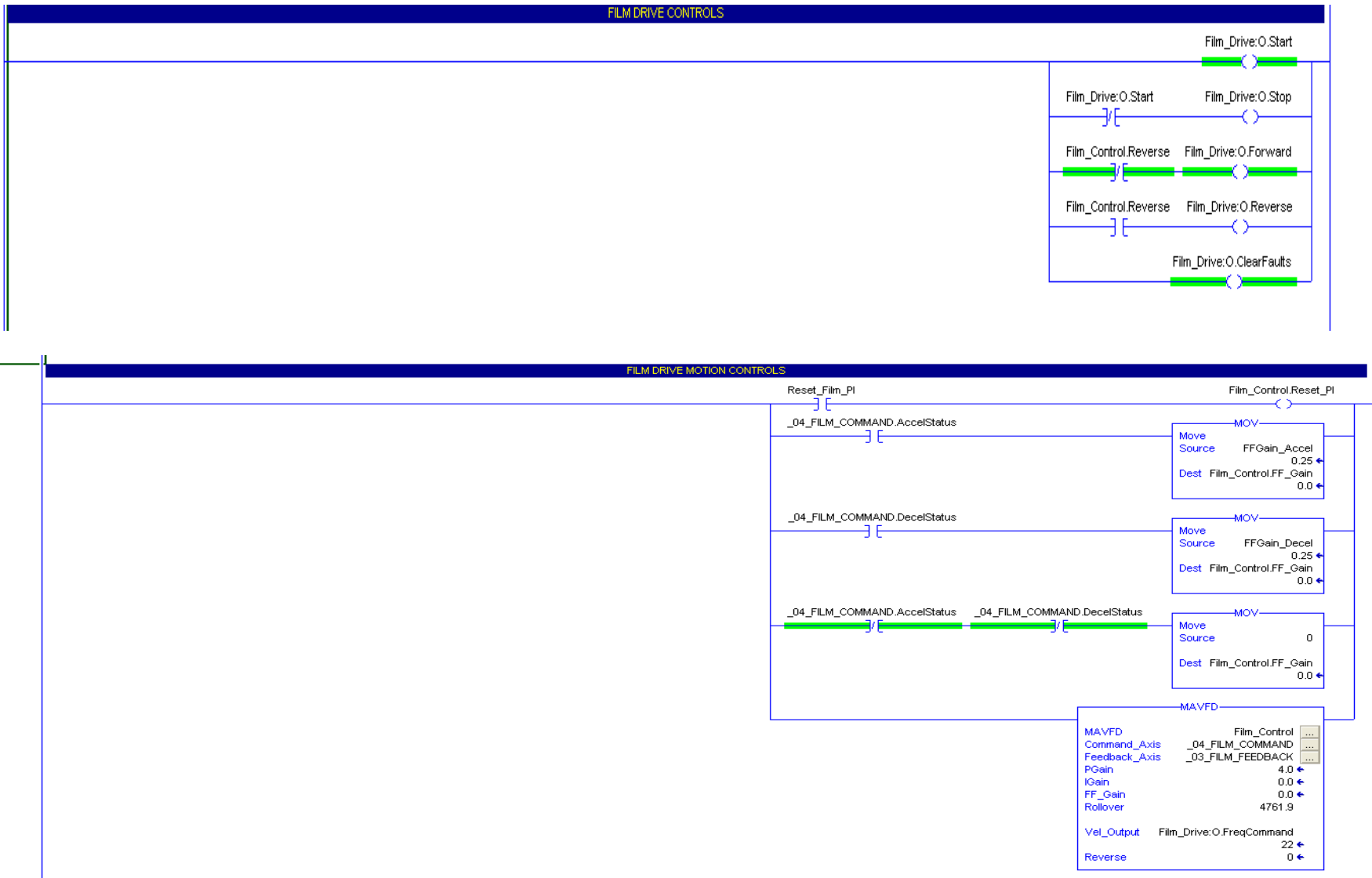
STANDARD Motion



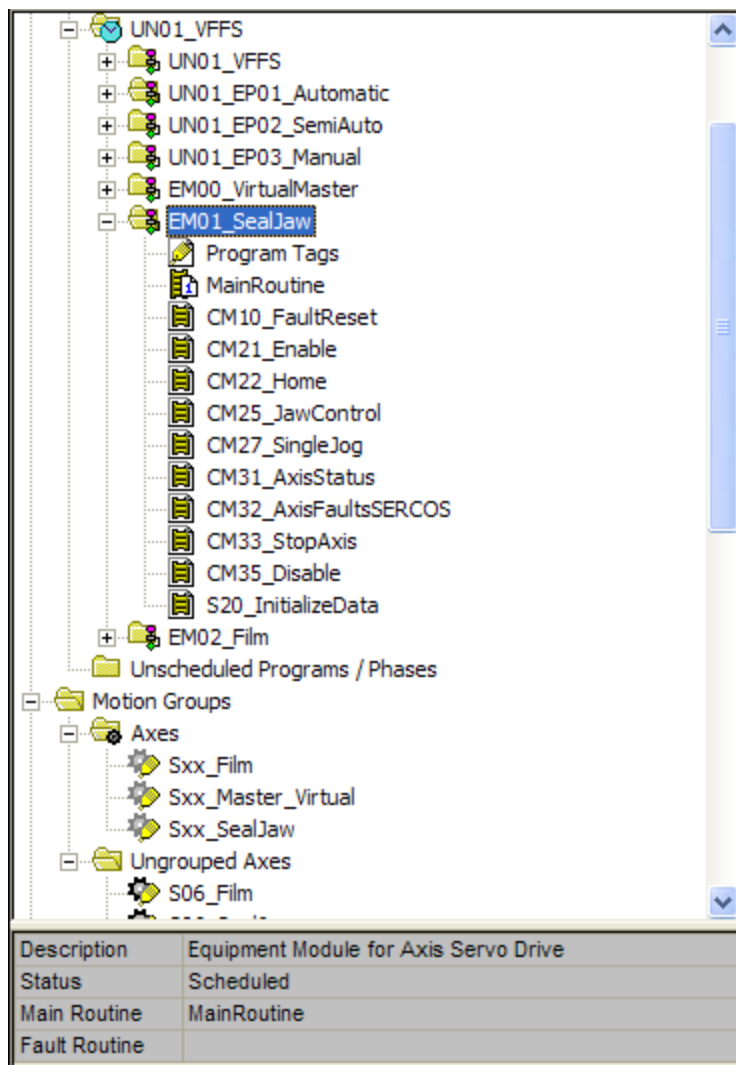
Motion using AOI



MAVFD: Using it in the Program 程序中的应用



VFFS template programme模版程序



- 基于PowerProgramming模块化编程模式
- 内嵌PhaseManage状态机控制流程，适用于包装行业国际标准
- 两种横封模式
- 开放性架构，客户可以方便添加自身的工艺特点

AOI Application

AOI_JawProfileCalc

AOI_JawProfileCalc	JawProfileCalc	...	(Sts_EN)
<VFFS.JawProfileCalc>			
Par_CycleRate	90.0	←	(Sts_PC)
Par_BagLength	360.0	←	
Par_PreSealAngle	30.0	←	(Sts_ER)
Par_PreSealTime	0.15	←	
Par_SealAngle	30.0	←	
Par_ManualSealTime	0.5	←	
Par_PostSealAngle	20.0	←	
Par_PostSealTime	0.1	←	
Par_JawRadius	200.0	←	
Par_AutoSealEnable	0	←	
Par_FilmSealCompression	0.0	←	
Out_JawStartTable	JawStartTable	...	
Out_JawStartProfile	JawStartProfile	...	
Out_JawRunTable	JawRunTable	...	
Out_JawRunProfile	JawRunProfile	...	
Out_JawStopTable	JawStopTable	...	
Out_JawStopProfile	JawStopProfile	...	
Out_Slope	0.11372116	←	
Sts_ERR	0	←	

AOI_PCamProfileDisplay

AOI_PCamProfileDispl...	JawProfileDisplayCalcs	...	(Sts_EN)
<VFFS.JawProfileDisplayCalcs>			
Cmd_Reset	0	←	(Sts_ER)
Cfg_HMIDisplayMode	0	←	
Cfg_CycleTime	0.666667	←	(Sts_MaxVelExceeded)
Par_CycleRate	90.0	←	
Inp_MaxVelocity	2400.0	←	(Sts_MinVelExceeded)
Inp_MaxAccel	30000.0	←	
Inp_MaxDecel	-30000.0	←	(Sts_MaxAccelExceeded)
Inp_Length	8	←	
Inp_Slope	JawProfileCalc.Out_Slope	←	(Sts_MaxDecelExceeded)
<VFFS.JawProfileCalc.Out_Slope>			
	0.11372116	←	
Inp_CamProfile	JawRunProfile	...	
Out_CamDisplay	JawProfileDisplayData		
<VFFS.JawProfileDisplayData>			
Inf_SlaveUnits	JawSlaveUnits		
<VFFS.JawSlaveUnits>			
Inf_MasterUnits	JawMasterUnits		
<VFFS.JawMasterUnits>			
Inf_Name	DisplayName		
<VFFS.JawProfileAOIName>			
Err_Value	0	←	

- 结构化编程
- 客户只需输入相关工艺参数，AOI 执行相关功能
- 可移植性，可以方便地在不同的程序段重复调用
- 安全性，可以为AOI设置密码，其他人看不到具体的AOI程序内容

CAM Profile

Calculate_CAM_Profiles

Calculate_CAM_Profiles Cal_Profile ... (Sts_EN)

Servo_Axis S02_N04_Sealer_Jaw ...

BagLength Bag_length ... (Sts_ER)

Seal_Time Seal_Time ... (Sts_DN)

Machine_Speed Speed 120.0

CAM_P cam_Vertical_Jaw ...

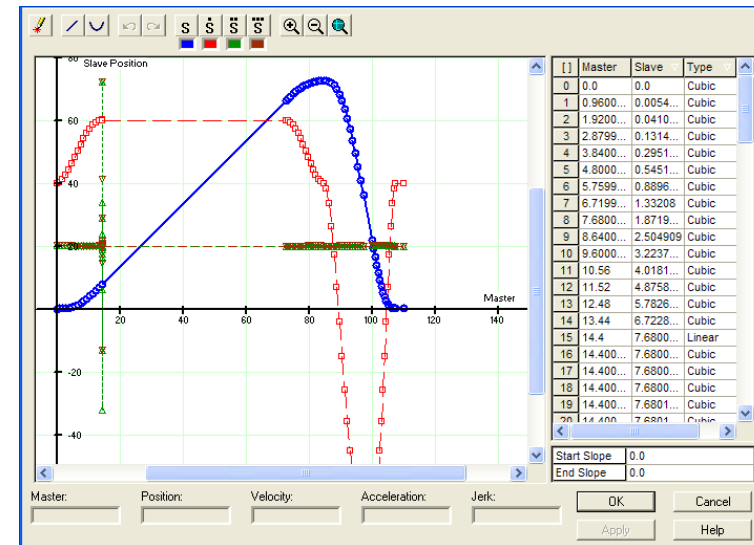
len1 Vertical_CAM_Length 96

len2 Horizontal_CAM_length 96

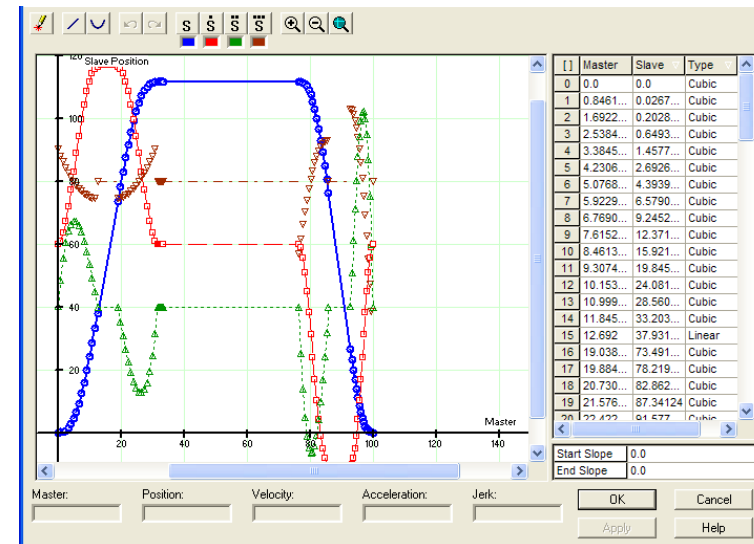
CAM_P1 cam_Horizontal_Jaw ...

HMI_Straffing_Enable Enable_Disable 0

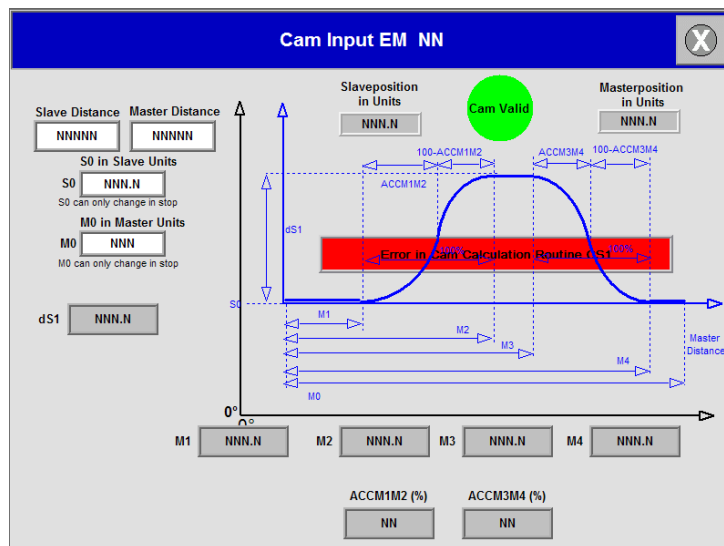
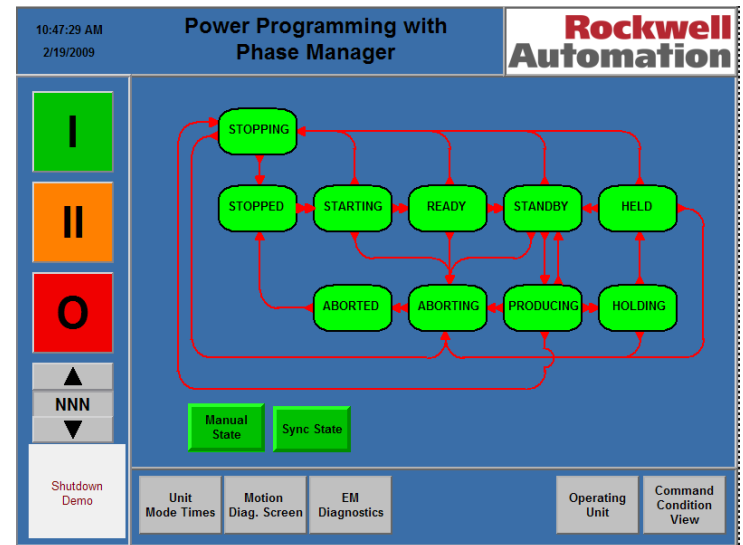
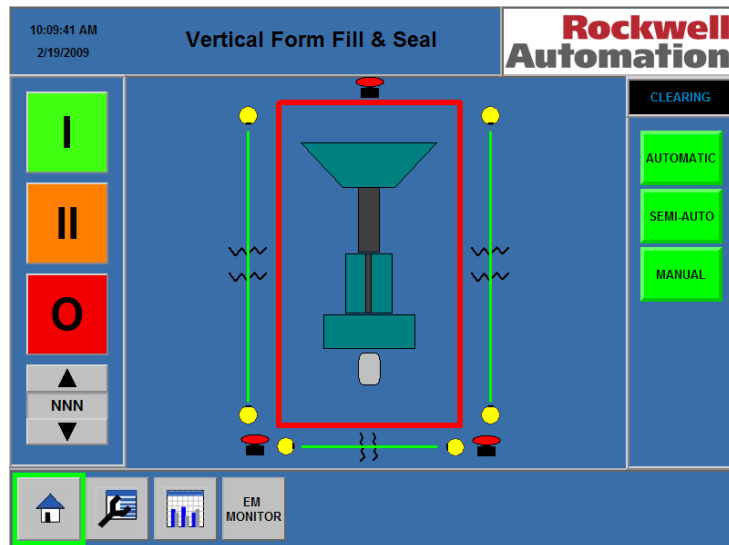
Straffing_Distance_Vertical Straffing_Distance 10.0



- Vertical Jaw横封模式的凸轮曲线设计
- Follow CAM上下跟随伺服运动曲线
- Seal CAM横封开合伺服运动曲线



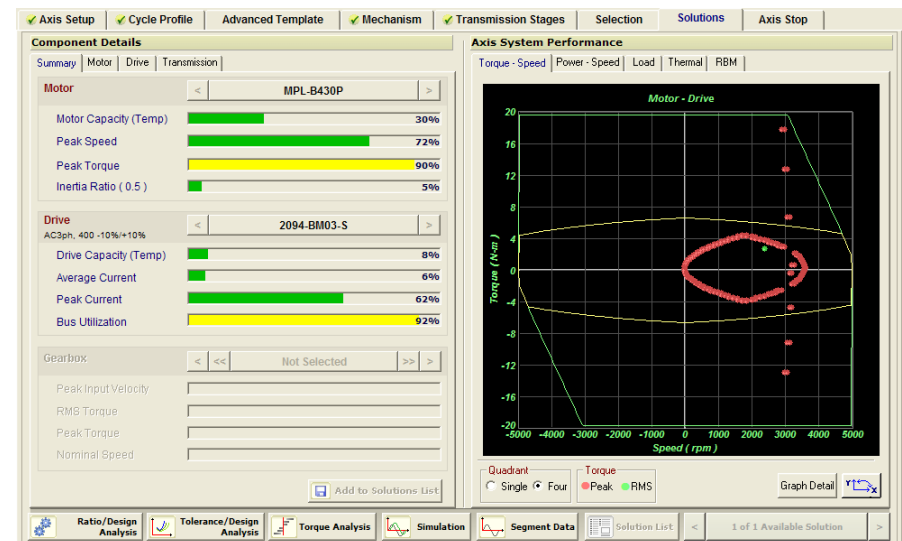
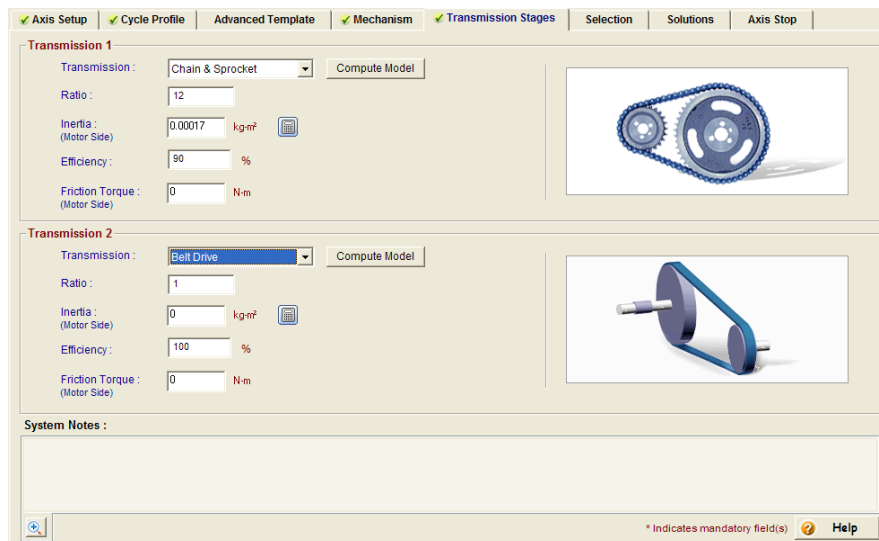
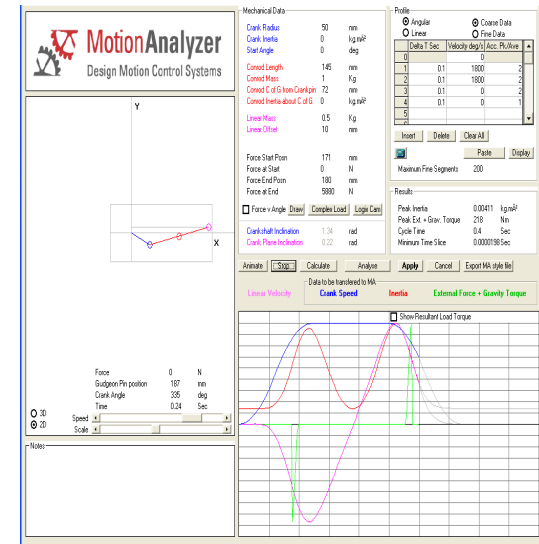
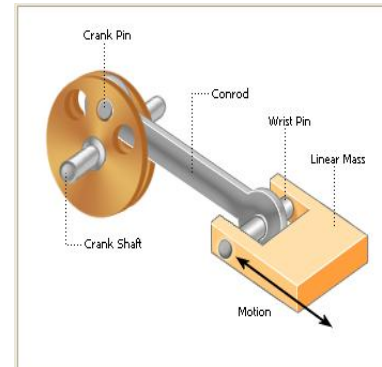
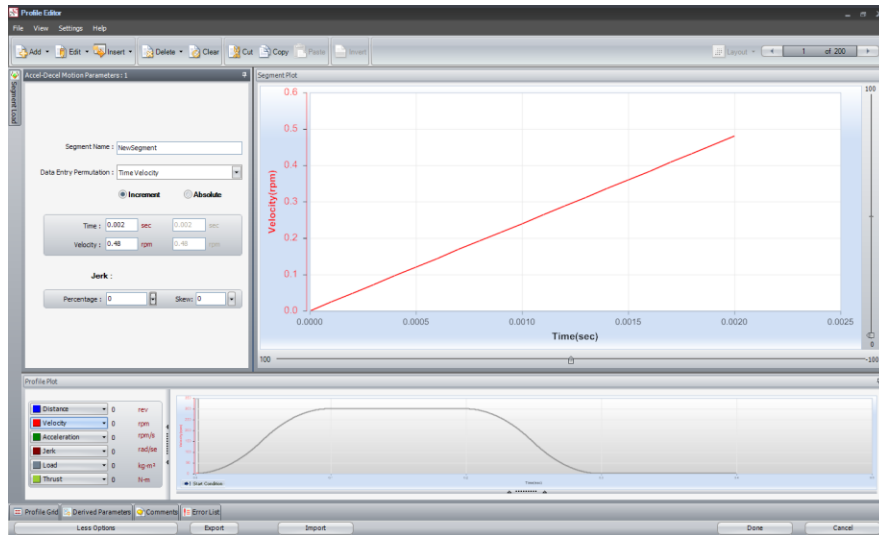
Template Display界面规划



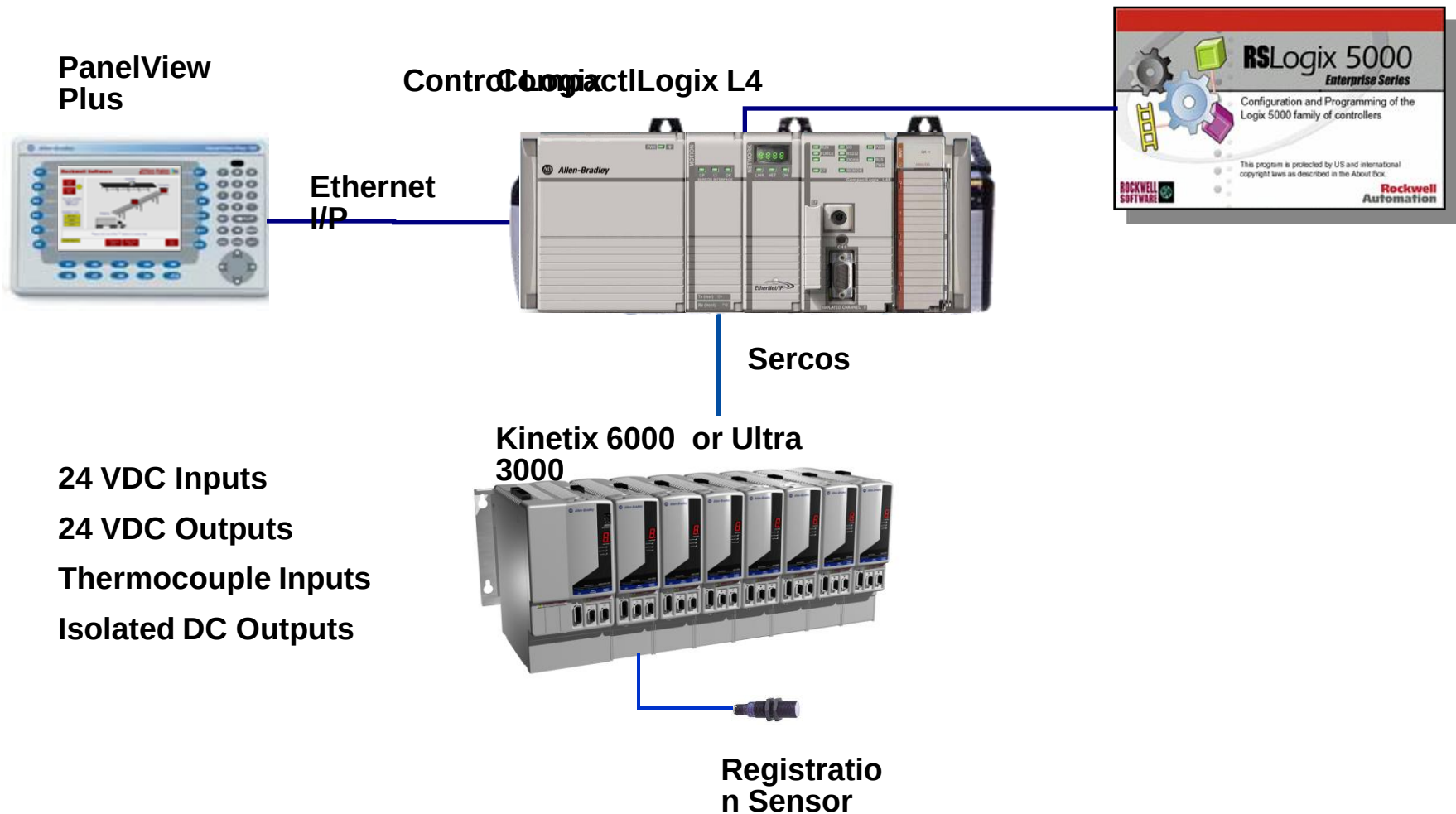
Command Condition Interface

Command	Condition	Command	Condition
☐ Check Selected	☐ Selected	☐ Activate Single Jog	☐ Activate Single Jog Done
☐ Check In Operation	☐ In Operation	☐ Activate Sync	☐ Activate Sync Done
☐ Check Faults	☐ Faulted	☐ Synchron Jog On	☐ Synchron Jog On Done
☐ Check Synchronization	☐ Synchronized	☐ One Cycle On	☐ One Cycle On Done
☐ Main Contactor On	☐ Main Contactor Done	☐ Semi Automatic On	☐ Semi Automatic Done
☐ Enable	☐ Enable Done	☐ Manual Wheel On	☐ Manual Wheel On Done
☐ Home	☐ Home Done	☐ Parameters Change	☐ Parameters Change Done
☐ Fine Synchronization	☐ Fine Synchronization Done	☐ Reference To 0	☐ Reference To 0 Done
☐ Check One Synchronization	☐ One Synchronization Done	☐ Abort	☐ Aborting Done
☐ Activate Run	☐ Activate Run Done	☐ Fault Reset	☐ Fault Reset Done
☐ Disable Cycling	☐ Disable Cycling Done		
☐ Enable Cycling	☐ Enable Cycling Done		
☐ Disable Product	☐ Disable Product Done		
☐ Enable Product	☐ Enable Product Done		
☐ Stop	☐ Stopping Done		
☐ Check 0 Speed	☐ In 0 Speed		
☐ Disable	☐ Disable Done		
☐ Main Contactor Off	☐ Main Contact Off Done		

Tool Software-Motion Analyzer



VFFS all servo Solution - Control Logix Migration全伺服方案



Rockwell Automation VFFS Experience 成功应用

- Examples of VFFS machines using Rockwell Automation Solutions 应用罗克韦尔方案的VFFS成功案例

- **Packaging Technologies**

- Chubmaker 4100 VFFS using CompactLogix & Kinetix

- **Prodo-Pak**

- PV-250 VFFS machine using ControlLogix & Kinetix 6

- **Rovema**

- Packaging OEM standarizes on Kinetix Integrated Motion
- Expands product line by 300% in less than 2 years

- **Triangle Package Machinery Co.**

- Advantage VFFS Bagger & Selectacom Weigher using ControlLogix
- VFFS Baggers using ControlLogix & Kinetix Servo Drives

- **Wolf Verpackungsmaschinen**

- VCI 250 VFFS powder bagging machine using ControlLogix

- **Wrapade**

- V-600 series VFFS machine using ControlLogix &



VFFS - Takeaway我们提供什么

- Hardware solutions to maximize your machine's performance
- 硬件解决方案来最优化您的机器性能
- Tools, training and knowledge to reduce manufacturing time and costs
- 工具，培训和相关知识来降低制造时间和费用
- Technology and domain expertise to help differentiate your machines
- 技术和相关领域的专家意见来帮助您定位您的机器
- Global support and business partnering to help you remain competitive

全球化支持和商业合作伙伴关系帮助你保持竞争力

Rockwell Automation has the broadest solutions and the expertise to help you optimize your VFFS machine

Rockwell Automation Global OEM Resources

罗克韦尔自动化全球OEM资源

- **Global Consulting Team**
 - Resources: 180
 - Extended team: 220
- **OEM Success**
 - Over 1600 OEMs engaged
 - 800 New opportunities
 - Helps machine builder be more successful by reducing Total Cost
- **OEM Team Linkage to End Users**
 - Press releases and value propositions
 - User project planning
 - Success tracking
- **Industry Leadership**
 - OMAC / ISA
 - PMMI
 - VDMA
 - UCIMA
 - MHIA
 - AIMCAL
 - INDIA
 - CEMATEX
 - International Standards Groups
- **OEM Tools**
 - Modular Programming Guidelines
 - Power Programming
 - Add-on Instruction (AOI) library
 - Sample Code and HMI Face Plates